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ANGULAR DEPENDENCE OF ALBEDO FROM STRATIFORM CLOUDS AS MEASURED BY TIROS IV SCANNING RADIOMETERS

by

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ABSTRACT

Pictures and radiation data from two orbits of TIROS IV have been used in this study to show the anisotropy in the albedo of low stratiform clouds. In order to scan the same clouds from two different directions we have used the radiation data when the satellite was in an alternating mode while the floor and wall sensors scanned the earth successively. To express the anisotropy we have used the specular angle, ω , and the backscattering angle, ψ_{\circ} , as parameters.

The results show that the albedo is dependent on these two parameters, particularly the specular angle.

1. Introduction.

The scattering and reflection of light in the atmosphere have been the subject of several studies. During World War II, Waldram (1945) made some experiments with a nephelometer and calculated the polar scatter index. He found a pronounced maximum at 0°, or in the forward scattering direction; a secondary maximum at 180°, or in the backward scattering direction; and a minimum around 90°, depending on the purity of the air. Deirmendjian (1962) obtained results very close to Waldram's; however, his minimum was located at a scattering angle near 110°. He also found a pronounced, relatively narrow maximum around 143°, which he explained as resulting from the fogbow, or white rainbow.

With the advent of the TIROS satellites with radiometers aboard, much radiation data have become available for such studies. Several authors have shown that radiation

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data obtained from Channel 2 (8-12 μ), combined with those from Channel 3 (0.25-6.0 μ), are useful in interpreting cloud systems and weather patterns on synoptic charts. The energy received by Channel 3 depends mainly on the reflecting surface, but this is not the only dependency. The energy is also a function of the solar zenith angle, the satellite zenith angle, and the relative azimuth.

Bartman et. al. (1964) measured the reflected and scattered radiation received by a TIROS IV radiometer from a high altitude (34 km) balloon flight in June, 1962. The radiation came from a rather uniform stratocumulus cover. Their readings covered scattering angles from 40° to 160°. Two maximum values, located at scattering angles of 40° and above 140°, respectively, were obtained. The minimum was located between 110° and 120°.

Larsen et. al. (1963) computed backscattering angles (the angle between incident and outgoing beam) for initial and complemental scans from one orbit of TIROS III. They kept the satellite zenith angles constant and assumed the solar zenith to be constant because of the small time interval. The backscattering angles for initial scans varied from 15° to 40°; for the complemental scans, there was only a slight variation around 70°. The energy values received from the same scanspot during the initial scans were higher than those received during the complemental scans. This is in agreement with the results of Deirmendjian and Bartman.

Viezee and Davis (1965) used one orbit of TIROS IV to show anisotropy in the backscattered light when the satellite is in an alternating mode (i.e., floor and wall sensor are scanning the earth successively). The scattering angles for floor and wall sensors varied from 131° to 78° and from 100° to 53° respectively. They found that the energy coming to the wall sensor was much higher than that coming to the floor sensor.

In this study we too have used two orbits of TIROS IV when the satellite was in an alternating mode, so that we could apply the data from both floor and wall sensors. On the basis of satellite pictures, synoptic observations, and satellite radiation data, we have been able to distinguish between different kinds of cloud surfaces. The purpose has been to see if there exist any significant differences in the reflecting properties of low stratiform cloud surfaces when they are viewed by the satellite from different directions. Although this problem has been the subject of much research, no completely satisfactory solution has as yet been offered.

2. Variation in Albedo of Stratoform Clouds as a Function of the Specular Angles.

The scattering and the backscattering angles, which are complementary, have been used by most authors to express the angular dependence of the outgoing shortwave radiation from the earth. The backscattering angle, $\psi_{\rm h}$, can be expressed by

$$\cos \psi_{\rm b} = \cos \zeta_{\star} \cos \zeta_{\bullet} + \sin \zeta_{\star} \sin \zeta_{\bullet} \cos \Delta \alpha \qquad (1)$$

where ζ_* and ζ_{\bullet} are the zenith angles of the sun and the satellite, respectively, and $\Delta\alpha$ is the relative azimuth (Fujita, 1963). The scattering and backscattering angles are useful parameters for expressing this angular dependence if the short-wave radiation picked up by the satellite is mainly scattered light. This may occur with very large solar zenith angles and with incoming light scattered by diffuse cirrus cloud surfaces. But in the case of a low stratiform cloud surface, which consists primarily of water droplets, reflection becomes by far the most important part of the short-wave radiation received by the satellite. Because of this we have found it useful to introduce another angle, ω , the specular angle. This is the angle between the radiometer axis and the specular reflection axis (Fig. 1). The specular angle is found from

$$\cos \omega = \cos \zeta_* \cos \zeta_* + \sin \zeta_* \sin \zeta_* \cos (180^\circ - \Delta \alpha)$$
 (2)

Since the maximum albedo, at least from a stratiform cloud surface, is assumed to coincide with the specular reflection axis, it becomes obvious that this angle has a significant physical meaning. If this maximum decreased uniformly out from the specular reflection axis in all directions, the specular angle would be the only independent variable. This is not plausible; it is more likely that the albedo is determined by a more complicated function of solar zenith angle, satellite zenith angle, and the relative azimuth. We will therefore only assume that the specular angle ω is a relatively good first approximation for the expression of this angular dependence, at least for small values of ω .

In the case of an alternating mode (Fig. 1), where the two sensors look at the earth from quite different directions, it is convenient to express the angular dependence with the specular angle for one of the sensors and with the backscattering angle for the other. The reason for this is the existence of a small backward scattered maximum in the direction towards the sun, and another advantage is that the variation in both angles is kept within relatively low values.

3. Results of Dual Measurements by Floor and Wall Sensors During Two TIROS IV Orbits.

When the TIROS satellite's spin axis is oriented approximately parallel to the earth's surface, the floor and the wall sensors scan the earth alternately. The wall sensor may scan an area first; then about three or four minutes later the floor sensor will scan approximately the same area. The overlapping area increases with a decreasing angle between the primary lines and the TSP track.

The orbits used in this study are nos. 143 and 200 of TIROS IV on 18 and 22 February 1962, respectively; and the geographical area covered is a portion of the Atlantic Ocean and West Africa, limited by 30°W to 5°W and 50°N to 15°N. The data are presented on sigma-t printout sheets produced by the Fujita scanning printer (Fujita, 1964). Longitude and latitude lines, as well as coastlines and other landmarks, are transferred to the printout sheets. Because of the conical scan geometry used in TIROS, the distortion of the grid lines will be in opposite directions for the floor and the wall sensors. This may cause confusion to the reader, who may prefer to see the data transferred to a standard map projection. On the other hand, this manner of presentation shows more clearly the many difficulties and uncertainties involved in the interpretation of the data, which may be effected by limb darkening space contamination, scan-spot size, etc.

Both of the analyzed orbits had useable photographs of the area of interest. These have been utilized in constructing the cloud composite charts in Figs. 2 and 11. The pictures have been transferred to the same kind of distorted map that was used for the floor sensor radiation data, because the floor sensor's principal lines and the optical principal lines nearly coincide. The high tilt made it rather difficult to construct a complete cloud chart from the pictures alone; in the uncertain areas, however, the available synoptic data combined with the radiation data have been used to complete the cloud charts. These areas have been singled out by hatching.

The pictures alone do not enable us to distinguish clearly between the different cloud types, but when combined with the synoptic data they give a fairly good idea about the clouds in question. The analyzed Channel 2 radiation data give additional information about the cloud heights, and can be used to confirm what has been learned from the two other sources. Using this method it was found that the clouds in the

areas indicated by A, B, C, in orbit 200 (Fig. 2) consisted of low stratiform clouds, while those in the areas indicated by D and E were altostratus or altocumulus, and cirrostratus, respectively. In orbit 143 (Fig. 11) the clouds in the areas indicated by F, G, and H all consisted of low stratiform clouds.

Figures 3 and 4 show the albedo, A, in percentage, obtained in orbit 200 from the wall and the floor sensors, respectively. The values have not been corrected for sensor degradation, because the correction that could be obtained would be rather uncertain, and also because we were mainly interested in the relative values between the wall and floor sensor. However, the readings have been corrected for 20% space contamination, and the values farther out towards the apparent horizon and beyond have been discarded. Isolines for specular angles and backscattering angles have been drawn on the wall and the floor sensor charts, respectively. The cloudy areas indicated by capital letters are outlined in both maps; these areas are seen to coincide with those of maximum albedo.

Figures 5 and 6 show the effective radiant emittances, \overline{W} , obtained in the same orbit from the wall and the floor sensor respectively. These values have been corrected for sensor degradation, but not for water vapor, ozone, limb darkening, etc. The readings in the cloudy areas A, B, and C indicate rather small differences from the virtually clear areas in the sea, while the readings in the areas D and E are significantly lower. The cirrus area E gives a minimum energy value of 18 watts m⁻² in both sensors, which corresponds to a temperature of approximately -25C. The soundings from the area indicate a cirrus temperature of -45C, which means that the energy coming to the satellite is strongly influenced by the background radiation.

Figures 12 and 13 show the albedo values obtained in orbit 143 from the wall and from the floor sensors, respectively. The explanations of Figs. 3 and 4, orbit 200, are more or less valid for these figures also.

4. Use of Effective Psuedo-radiant Emittance in Determining Cloud Albedo Excluding Background Albedo.

As the composite cloud charts in Figs. 2 and 11 indicate, the cloud covers investigated are not all solid, but instead are broken or scattered. The albedo A measured by Channel 3 from many of the areas therefore must have originated partly from the clouds and partly from the background. In order to eliminate the effect

of the background albedo we will make use of Eq. (3) which was derived from Eqs. (11) and (13) of Fujita and Grandoso (1966). Thus,

$$A_{c} = \frac{1}{\beta \overline{\pi}} (\overline{\pi} \beta A_{b} + \overline{B}_{b} - \overline{B}_{c})$$
 (3)

where A_c is the cloud albedo, β is a coefficient varying between 0 and 1.0 depending upon the type and thickness of the cloud, and is equivalent to ρ in Fujita and Grandoso; A_b is the background albedo, B_b is the effective background radiant emittance, and B_c is the effective cloud radiant emittance.

$$\overline{\pi} = \frac{\overline{B}_b - \overline{W}}{A - A_b}$$

is defined as the effective pseudo-radiant emittance; this is found to be a useful quantity in determining the type of clouds. It can immediately be seen that the value of $\overline{\pi}$ increases with increasing cloud heights, and it also increases with decreasing cloud thickness and increasing cloud diffuseness. From Eq. (3) the cloud albedo can be found, if β , A_b , B_b , and B_c are known. In this particular case we are mainly interested in the albedo from low stratiform clouds over a water surface. In the case of low, relatively thick stratus clouds β is expected to be approximately equal to 1 and the background albedo from water A_b is assumed to equal 0.01 at least when the solar zenith angle is less than 60° . If we take the ratio between the cloud albedo for the wall sensor and that for the floor sensor under these conditions, we obtain

$$\frac{\Delta^{WL}}{\Delta^{FL}} = \frac{\overline{\pi}^{FL}}{\overline{\pi}^{WL}}$$
 (4)

This means that we only have to compute $\overline{\pi}$ for both floor and wall sensors in order to obtain the ratio between the cloud albedo coming to the two sensors. In order to compute $\overline{\pi}$ we must know the background albedo A_b and the effective background radiant emittance B_b . In Figs. 7 and 8 the background albedo A_b for both sensors in orbit 200 has been estimated. The water albedo has been assumed to be 0.01, which is plausible, as long as the solar zenith angle stays below 60°. The Sahara Desert, which is indicated by stippling on the chart, gives a very high background albedo A_b , which more or less coincides with the actual albedo A because the area is apparently cloudless. In Figs. 9 and 10 the effective background radiant emittances have been estimated for both wall and floor sensor in orbit 200. The effective radiant emittance from water is close to 35 watts m⁻² for the main part of the area, except

near the horizon where the limb darkening effect occurs. It may also be noted that the Sahara Desert is relatively cold compared to its surroundings; this is due to the early time of day and the high reflectance from the sand. From the maps in Figs. 3, 5, 7, and 9, and from the maps in Figs. 4, 6, 8, and 10, we are able to compute $\overline{\pi}$ for wall sensor and floor sensor in orbit 200, respectively.

5. Discussion of Anisotropic Albedo Obtained.

The results of the $\overline{\pi}$ computations are shown in Figs. 14 and 15 for orbit 200 and in Figs. 16 and 17 for orbit 143. The values of $\overline{\pi}$ in the stratus cloud areas A, B, and C in Figs. 14 and 15 are relatively low and uniform for both sensors; moreover, the values of $\overline{\pi}^{\text{WL}}$ seem to be mainly a little lower than those of $\overline{\pi}^{\text{FL}}$. The values of $\overline{\pi}$ in the cirrus area are high in both sensors, but relatively the $\overline{\pi}^{\text{FL}}$ values are almost twice as large as those of $\overline{\pi}^{\text{WL}}$. The stratocumulus cloud cover at D shows values of $\overline{\pi}$ about three times as high in the floor sensor as in the wall sensor. This latter may be caused by several things; the satellite zenith angle for the wall sensor is above 70° in this area, which makes the computation of $\overline{\pi}$ uncertain because of limb darkening, scanspot size, etc.; furthermore the relative azimuth is close to 180° in the area and the specular angle is small, around 20°. In Figs. 16 and 17 the $\overline{\pi}$ values for wall and floor sensors in orbit 143 are presented. These values are consistently a little lower than those from the stratus area in orbit 200; this is mainly due to higher albedo but partly due to lower cloud heights.

To find the angular dependence of the albedo we have used Eq. (4) for the areas covered with low stratiform clouds over water. The areas of cirrus and altocumulus have been excluded, primarily because we do not know the value of β for these clouds. The results of these computations are shown in Figs. 18 and 19. The ratio A_c^{WL}/A_c^{FL} (between the cloud albedo obtained by the wall sensor and the cloud albedo obtained by the floor sensor) has been plotted as a function of the specular angle ω^{WL} for the wall sensor, and the backscattering angle ψ_b^{FL} for the floor sensor. The number in each square is an average over a 10° interval, for both angles; the number in parentheses indicates how many values were averaged.

In orbit 200 the backscattering angles ψ_b^{FL} remain almost constant between 10° and 20°, while the specular angles ω^{WL} vary from 40° down to almost 0°. The ratio A_c^{WL}/A_c^{FL} should then be primarily a function of the specular angle. As can be seen, the ratio increases gradually for lower values of ω^{WL} ; it reaches a maximum of

1.55 when the specular angle is between 0° and 10°. In orbit 143 both the backscattering angle and the specular angle vary between 10° and 70°. As in orbit 200, the ratio A_c^{WL}/A_c^{FL} increases as the specular angle decreases, and it also increases as the backscattering angle decreases. In the regions of 10° to 20° backscattering angle, and of 40° to 70° specular angle, the ratio is close to 1 which should indicate isotropic conditions.

6. Conclusions.

Evidence of anisotropy in the albedo from low stratiform clouds seems obvious from the results obtained in the two orbits. Since these clouds consist mainly of water droplets, reflection is by far the most important part of the short-wave radiation measured by the satellite. The specular angle ω , which is a measure of the deviation from the specular reflection axis, seems to be an important and convenient parameter to express this dependence, even though we believe the exact relationship to be a more complicated function of the solar zenith angle, satellite zenith angle, and relative azimuth. The results obtained do not allow many generalizations, because of the small sample of data, but it seems evident that the anisotropy becomes more and more significant as the specular angle ω decreases. The orbit 143 data seem to suggest nearly isotropic conditions when the specular angle ω^{WL} exceeds 40° - 50° , but this certainly has to be substantiated by further research. The backward scattering or reflecting maximum towards the sun seems also to be a reality, since the ratio $A_c^{\text{WL}}/A_c^{\text{FL}}$ increases with decreasing backscattering angles ψ_c^{FL} .

The data from cirrus and altocumulus areas in orbit 200 also suggest a strong anisotropy in the albedo. Investigation of these clouds is, however, more complex, as their coefficient β is less than 1, and as their tops consist mainly of ice crystals which may scatter the light more than they reflect it.

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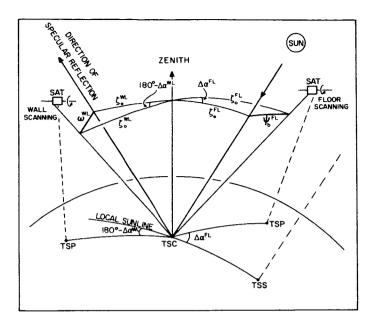


Fig. 1. Schematic view of the satellite scanning the same spot on the earth from two different positions. The specular angle, $\omega^{\rm WL}$, and the backscattering angle, $\psi^{\rm FL}_{\rm b}$, are indicated by heavy lines.

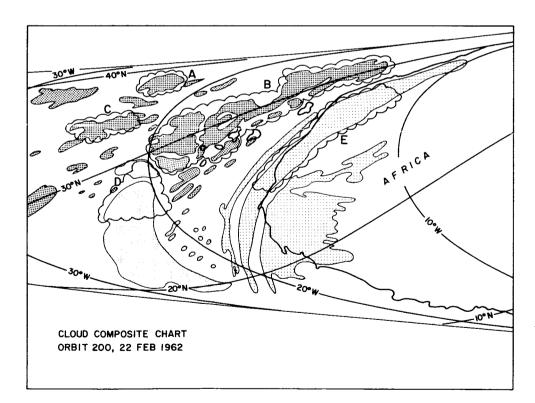


Fig. 2. Composite cloud chart from Orbit 200, TIROS IV, 22 February 1962. The clouds in the areas indicated by A, B, and C consist of low stratiform clouds, whereas the clouds in the areas D and E consist of altocumulus and cirrostratus, respectively.

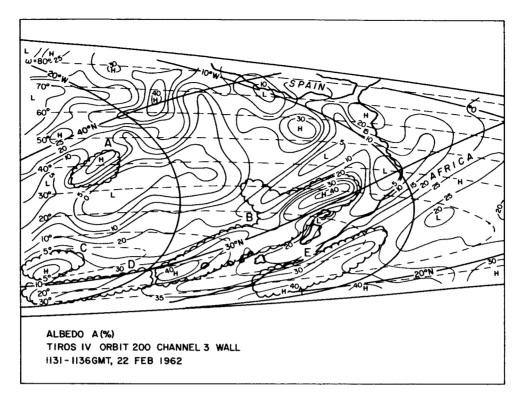


Fig. 3. Patterns of Channel 3 (0.25-6.0 μ) albedo A (%) received by the wall sensors during Orbit 200, TIROS IV, 22 February 1962. Isolines for the specular angle ω^{WL} are indicated by dashed lines. Longitude and latitude lines are drawn for every 10° interval, and coastlines are indicated by heavy lines.

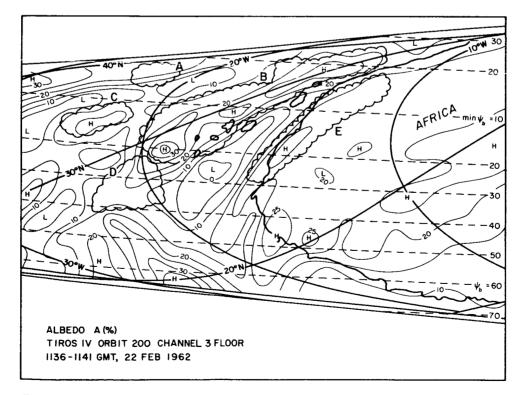


Fig. 4. Patterns of Channel 3, albedo A (%) received by the floor sensor during Orbit 200, TIROS IV, 22 February 1962. Isolines for the backscattering angle, ψ_b^{FL} , are indicated by dashed lines.

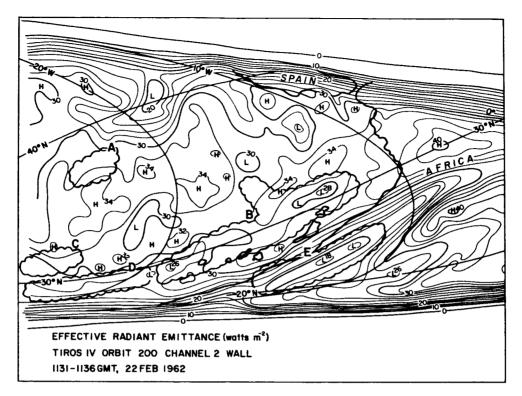


Fig. 5. Patterns of Channel 2 (8-12 μ) effective radiant emittance \overline{W} (watts m⁻²) received by the wall sensor during Orbit 200, TIROS IV, 22 February 1962. Longitude and latitude lines are drawn for every 10° interval and the coastlines are indicated by heavy lines.

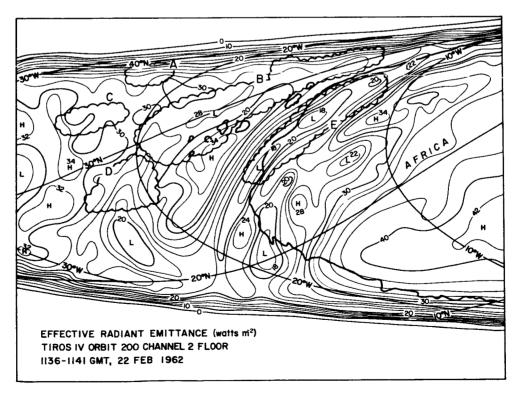


Fig. 6. Patterns of Channel 2 effective radiant emittance \overline{W} (watts m^{-2}) received by the floor sensor during Orbit 200, floor sensor, TIROS IV, 22 February 1962.

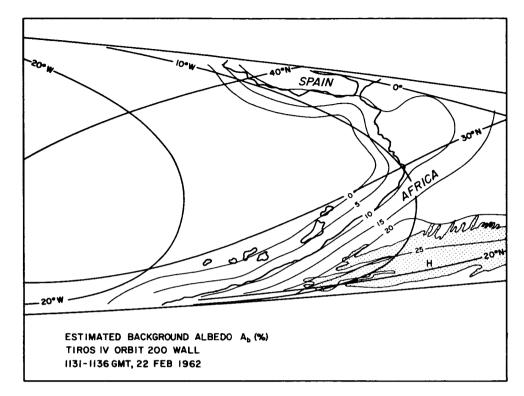


Fig. 7. Patterns of estimated background albedo $A_b(\%)$ for the wall sensor, Orbit 200, TIROS IV, 22 February 1962. The stippled area represents the Sahara Desert.

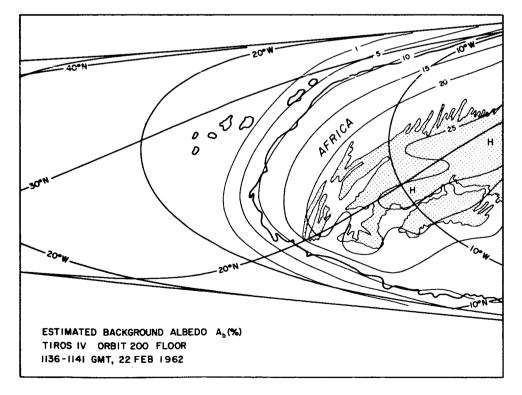


Fig. 8. Patterns of estimated background albedo A_h (%) for the floor sensor, Orbit 200, TIROS IV, 22 February 1962.

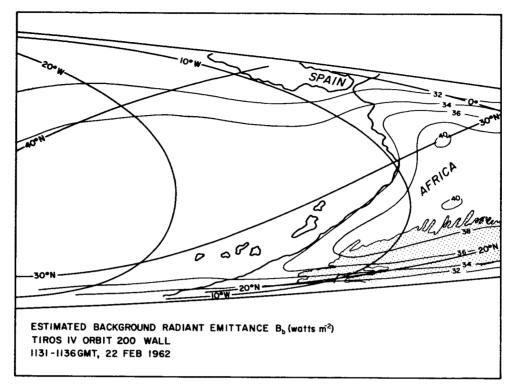


Fig. 9. Patterns of estimated effective background radiant emittance \overline{B}_b (watts m⁻²) for the wall sensor, Orbit 200, 22 February 1962. The stippled area represents the Sahara Desert.

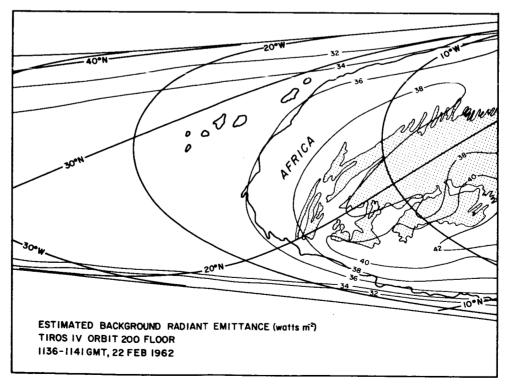


Fig. 10. Patterns of estimated effective background radiant emittance \overline{B}_b (watts m⁻²) for the floor sensor, Orbit 200, TIROS IV, 22 February 1962.

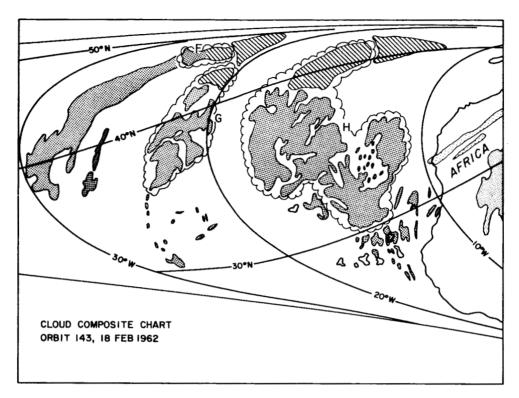


Fig. 11. Composite cloud chart from Orbit 143, TIROS IV, 18 February 1962. The clouds in the areas indicated by F, G, and H consist mainly in low stratiform clouds.

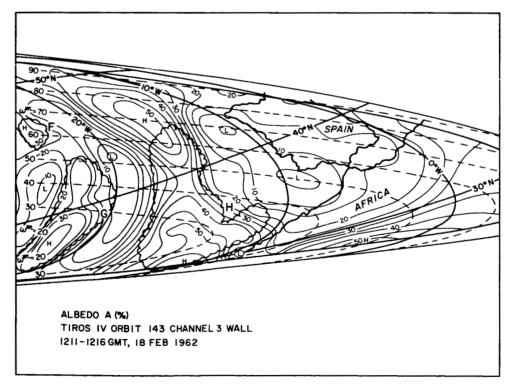


Fig. 12. Patterns of Channel 3 albedo A (%) received by the wall sensor during Orbit 143, TIROS IV, 18 February 1962. Isolines for the specular angle ω^{WL} are indicated by dashed lines.

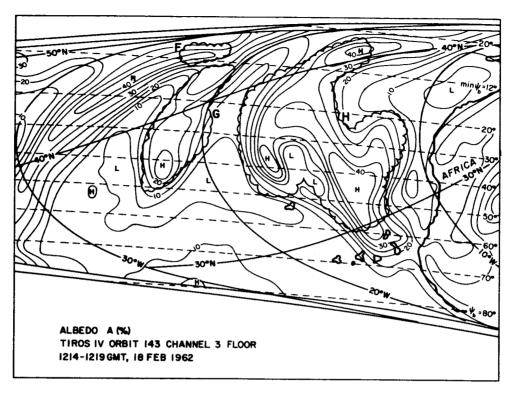


Fig. 13. Patterns of Channel 3 albedo A (%) received by the floor sensor during Orbit 143, TIROS IV, 18 February 1962. Isolines for the backscattering angles ψ_b^{FL} are indicated by dashed lines.

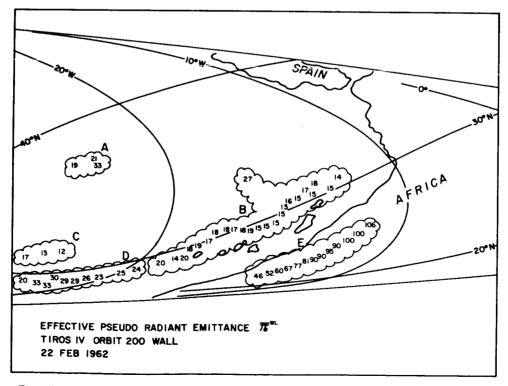


Fig. 14. Computed effective pseudo-radiant emittance $\overline{\pi}^{\text{WL}}$ of the cloudy areas indicated by A, B, C, D, and E for the wall sensor, Orbit 200, TIROS IV, 22 February 1962.

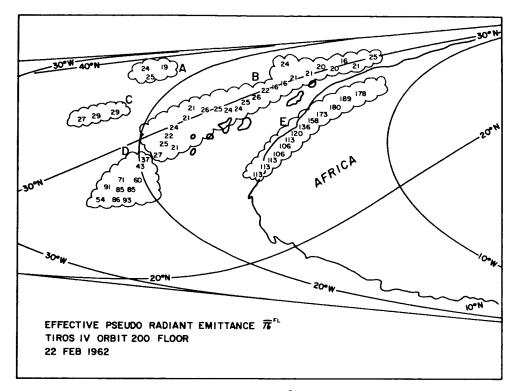


Fig. 15. Computed effective pseudo-radiant emittance $\overline{\pi}^{\text{fl}}$ of the cloudy areas indicated by A, B, C, D, and E for the floor sensor, Orbit 200, TIROS IV, 22 February 1962.

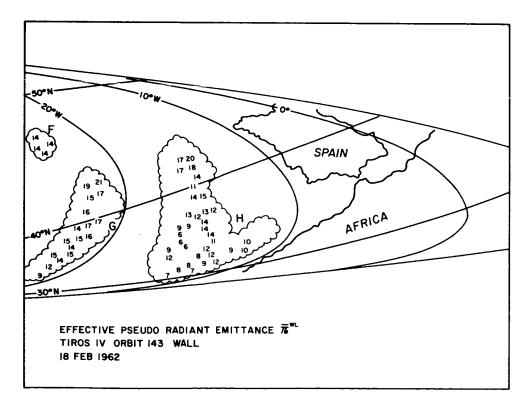


Fig. 16. Computed effective pseudo-radiant emittance $\overline{\pi}^{\text{WL}}$ of the cloudy areas indicated by F, G, and H for the wall sensor, Orbit 143, TIROS IV, 18 February 1962.

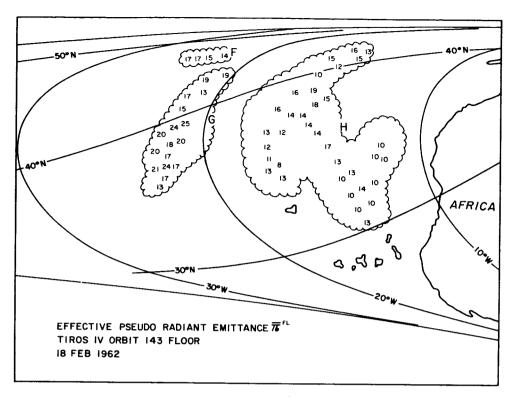


Fig. 17. Computed effective pseudo-radiant emittance $\overline{\pi}^{FL}$ of the cloudy areas indicated by F, G, and H for the floor sensor, Orbit 143, TIROS IV, 18 February 1962.

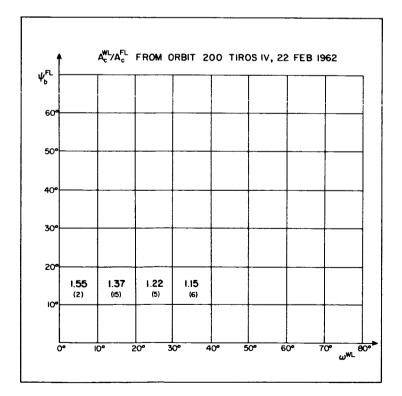


Fig. 18. The ratio, $A_c^{\text{ML}}/A_c^{\text{FL}}$, between the cloud albedo to the wall sensor and the cloud albedo to the floor sensor as a function of the specular angle of the wall sensor, ω^{ML} , and the backscattering angle of the floor sensor, ψ_b^{FL} . TIROS IV, Orbit 200, 22 February 1962.

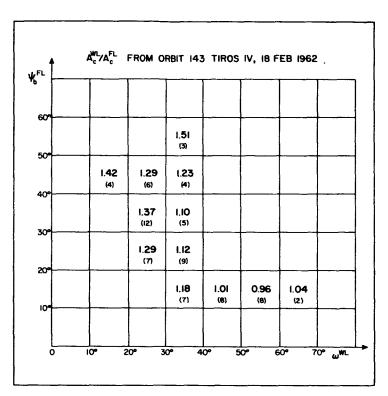


Fig. 19. The ratio, A_c^{WL}/A_c^{FL} , plotted as a function of the specular angle ω^{WL} and the backscattering angle ψ_b^{FL} . TIROS IV, Orbit 143, 18 February 1962.

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